

Ross Creek- Smythes Creek Community Plan 2017 -2020

What is Community Planning?

Community Planning is a process where community members come together and take action to improve their community. Community members develop a community plan that outlines projects they will undertake to make their town a better place to live.

Golden Plains Shire Council supports Community Planning by providing a professional facilitator who assists communities, as well as grants to help implement the projects in the community plan.

Currently 23 communities across the Shire are helping make their towns a great place to live through community planning. To learn more about community planning visit the goldenplains.vic.gov.au.

Community Coordinators

Local residents known as Community Coordinators, volunteer their time to coordinate the development and implementation of a community plan. The following community members are Community Coordinators for this Ross Creek - Smythes Creek Community Plan.

Rosemary	Barnett	0439 506 494	rbrosebarnett@gmail.com
Gerold	Martens	0423291446	geroldwm@gmail.com
Andrew	Carnie	0498965482	Andrew_carnie@hotmail.com
Cathy	Bushell	0408108957	Cjbushell1@gmail.com
Carol	Drury	0417 118 159	caroldrury56@gmail.com

Please contact your Coordinators for more information about this plan or for the date of upcoming meetings that you are welcome to attend.

Date plan was adopted

October 2017

Plan start date

October 2017

Plan finish date

October 2020

Celebrating Ross Creek – Smythes Creek



“We couldn’t be prouder of Golden Plains Shire Community Coordinators, and everyone involved in community planning – they go above and beyond for their communities and they’re a big reason why Golden Plains is such a great place to live and visit.”

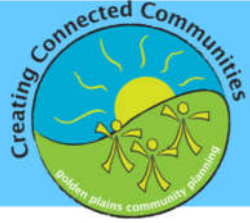
Cr Des Phelan, Mayor



How was this Plan developed?

Preparation to develop this community plan commenced in May 2017. The Ross Creek – Smythes Creek community were asked for ideas and projects via a survey distributed to each resident. 55 survey responses were then collated.

A public forum was then held on the 21st of July at which those present (28 residents) voted to establish the top priorities for the Plan. From this process the following Projects were established as the priorities for the Ross Creek – Smythes Creek Community Plan 2017 – 2020.



2017-2020 Community Plan Key Projects

Health and Wellbeing

To promote community connectedness and opportunities to enhance the health and wellbeing of community members by establishing such things as:

- Safe bike and walking tracks / paths
- Exercise stations
- Upgrades and equipment to Recreation Reserve

SEED Funding allocated \$2,000

Environmental Sustainability

Support our local Landcare Group in:

- Reserve upgrades and maintenance
- Boardwalk to supplement current pathways
- Fundraising opportunities

SEED Funding allocated \$1,000

Skate Park &/or BMX Track

Work towards the establishment of a Skate Park and/or BMX track in the local area

SEED Funding allocated \$2,000



Community Connectedness

Create opportunities for the community to come together by establishing and supporting such things as:

- Avenue of Honour celebrations August 2018
- Markets or car boot sales
- Activities in the Hall
- Community get togethers
- Activities for young people and kids
- Workshops and learning opportunities
- Partnership projects with the school

SEED Funding allocated \$2,000

Town Information

Further develop and promote electronic communication options for our town to include:

- Local history
- Cultural and heritage information
- Local events
- Information for new residents
- Links to services / committees in the local area

SEED Funding allocated \$500

Roads

Advocate for:

- Upgrade and improvements of local roads
- Bus Shelter
- Lighting on appropriate roads

The Ross Creek – Smythes Creek Community Plan is proudly supported by



Disclaimer; If major changes to the Community Plan projects need to be made within the life of the plan, Coordinators will conduct public process before making these changes

